# Transformer and Large Language Models

Instructor: Lei Wu<sup>1</sup>

Mathematical Introduction to Machine Learning

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<sup>&</sup>lt;sup>1</sup>School of Mathematical Sciences; Center for Machine Learning Research

#### Transformer

#### Transformers

- were introduced in Attention is all you need (Vaswani et al., NeurIPS 2017);
- have revolutionized NLP, CV, robotics and many applications;
- have enabled the creation of powerful LLMs such as GPT-4;
- hold the promise of unlocking the potential for AGI (artificial general intelligence).



Consider a simple block for sequence modeling:

$$X := (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n) \stackrel{\mathcal{T}}{\mapsto} Y := (\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n).$$

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Attention (simplified, adaptive/selective weighted average):

$$\mathbf{y}_i = f\left(\sum_{j=1}^n w_{i,j}(X)\mathbf{x}_j\right),\,$$

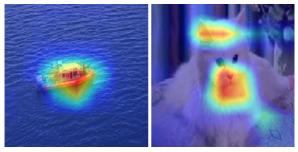
where  $W(X) = (w_{i,j}(X)) \in \mathbb{R}^{n \times n}$  satisfies  $\sum_{j=1}^{n} w_{i,j}(X) = 1$ .

### Attention Mechanism (Cont'd)

We often call  $w_{i,j}(X)$ 's the **attention score** and we want

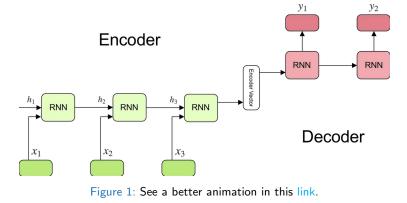
the attention scores  $(w_{i,1}(X), w_{i,2}(X), \dots, w_{i,n}(X))$  to be sparse (i.e., selective).

• Attention in vision modeling:



### Attention Mechanism (Cont'd)

Attention in machine translation (cross attention) <sup>2</sup>:



<sup>&</sup>lt;sup>2</sup>Bahdanau et al., Neural Machine Translation by Jointly Learning to Align and Translate, ICLR 2015.

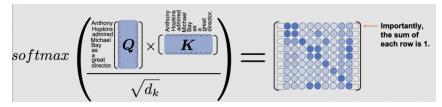
#### Self-Attention via Dot-Product

- Let  $X = (\mathbf{x}_1, \dots, \mathbf{x}_n) \in \mathbb{R}^{d \times n}$  be our input sequence. We often call  $\{\mathbf{x}_i\}$  tokens.
- A self-attention  $\mathbb{A}: \mathbb{R}^{d \times n} \mapsto \mathbb{R}^{n \times n}$  outputs an attention-score map  $P = \mathbb{A}(X)$ . The most popular choice is

$$\mathbb{A}_{W_{K},W_{Q}}(X) = \sigma\left(\frac{1}{\sqrt{d}}(W_{K}X)^{\top}(W_{Q}X)\right) \in \mathbb{R}^{n \times n},$$

where

- $W_K, W_Q \in \mathbb{R}^{d_{key} \times d}$  are the key and query weight matrices, which are learned from data.
- $\sigma$  denotes the softmax normalization performed in a column-wise manner, ensuring the column represent a selective average.



#### Self-Attention via Dot-Product (Cont'd)

The dot-products are implemented in a token-wise manner (can be naively paralleled):

$$\mathbf{k}_{i} = W_{K}\mathbf{x}_{i}, \mathbf{q}_{j} = W_{Q}\mathbf{x}_{j} \text{ for } i, j \in [n]$$
$$(\mathbb{A}_{W_{K}, W_{Q}}(X))_{i, j} = \frac{e^{\mathbf{k}_{i}^{\top}\mathbf{q}_{j}}}{\sum_{i'=1}^{n} e^{\mathbf{k}_{i'}^{\top}\mathbf{q}_{j}}}$$

- The attention scores are determined by the **dot-product correlation** among tokens. In principle, one can also propose other alternatives.
- A single-head attention layer SA :  $\mathbb{R}^{d \times n} \mapsto \mathbb{R}^{d \times n}$  is given as follows

$$\mathsf{SA}_{W_K,W_Q,W_V}(X) = V\sigma(QK),$$

where Q, K, V are called the query, key, value matrices, respectively and given by

$$Q = W_Q X, \quad K = W_K X, \quad V = W_V X.$$

#### **A Transformer Block**

• A transformer block defines a sequence-to-sequence map

$$X = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n) \in \mathbb{R}^{d \times n} \mapsto Y = (\mathbf{y}_1, \mathbf{y}_2, \dots, \mathbf{y}_n) \in \mathbb{R}^{d \times n}.$$

• This maps consists of two blocks:

$$Y = \mathbb{F}(X + \mathtt{MHA}(X)),$$

where

• Multi-head attention (MHA)

$$\mathtt{MHA}(X) := \sum_{h=1}^{H} W_O^h \mathtt{SA}^h(X).$$

• Tokenwise feed-forward networks (FFN):

$$\mathbb{F}(Z) := (h(\mathbf{z}_1), h(\mathbf{z}_2), \dots, h(\mathbf{z}_n)) \in \mathbb{R}^{d \times n}.$$

In practice,  $h : \mathbb{R}^d \mapsto \mathbb{R}^d$  is often chosen to be a two-layer MLP with hidden size  $d_{FF}$ .

$$h(\mathbf{z}) = W_1^{\top} \operatorname{ReLU}(W_2 \mathbf{z} + \mathbf{b}),$$

where  $W_1, W_2 \in \mathbb{R}^{d_{\mathrm{FF}} \times d}$  and  $\mathbf{b} \in \mathbb{R}^d$ .

#### Transformer

• Input: Linear embedding to change the dimension of each token.

$$X^{(0)} = VX$$
 with  $V \in \mathbb{R}^{d_{\text{model}} \times d}$ .

• Main block:

$$X^\ell = \mathbb{F}^{(\ell)}(X^{(\ell-1)} + \mathrm{MHA}^{(\ell)}(X^{(\ell-1)})), \quad 1 \leq \ell \leq L.$$

• Ouput: The output format depends on the tasks. In classification, we may

$$f(X) = p(\mathbf{x}_1^{(L)}),$$

where p can be either a linear layer or small MLP.

• Architecure hyperparameters:  $d_{\text{model}}$ , H, L,  $d_{\text{key}}$ ,  $d_{\text{FF}}$ . In practice, a common choice  $d_{\text{FF}} = 4d_{\text{model}}$ ,  $d_{\text{key}} = d_{\text{model}}/H$ .

### Absolute Positional Embedding (APE)

Transformers are still inherently **permutationally invariant** and we need to modify transformers by injecting position information.

The most natural way of injecting position information is using **absolute positional** embedding (APE): let  $\mathbf{r}_i \in \mathbb{R}^d$  denote the information for token *i*:

$$\mathbf{x}_i \rightarrow \mathbf{x}_i + \mathbf{r}_i$$

- Learnable APE:  $\mathbf{r}_i$  are parameters to be learned.
- One-hot APE:  $\mathbf{r}_i = \mathbf{e}_i$  where  $\mathbf{e}_i$  is the one-hot label with 1 in the *i*-th coordinates and zero else.
- Sinusoidal APE:

$$\mathbf{r}_i = \left(\sin(i), \cos(i), \sin(i/c), \cos(i/c), \dots, \sin(i/c^{2i/d}), \cos(i/c^{2i/d})\right) \in \mathbb{R}^d,$$

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APE is rarely used in practice anymore due to:

- APE can not handle input sequence longer than that used in training.
- In many real problems, it is "relative distance" matters.

#### Relative Positional Embedding (RPE)

• Additive RPE: Let  $E = (W_K X)^\top (W_Q X) \in \mathbb{R}^{n \times n}$  be the pre-softmax attention weights. Then, we inject relative position information by

$$\mathbb{A}(X) = \sigma(E - P),$$

where 
$$P = (h(j-i))_{i,j} \in \mathbb{R}^{n \times n}$$
.

In T5 RPE chooses

$$h(t) = \begin{cases} |t| & \text{if } |t| \le B/2\\ \frac{B}{2} + \frac{B}{2} \left\lfloor \frac{\log\left(\frac{|t|}{B/2}\right)}{\log\left(\frac{D}{B/2}\right)} \right\rfloor & \text{if } \frac{B}{2} \le |t| \le D\\ B-1 & \text{if } |t| \ge D \end{cases}$$

In Alibi RPE,  $h(t) = -\alpha |t| + \beta$ . Where the  $\alpha$  and  $\beta$  can be either learnable or fixed.

 Currently, the most popular one is the rotary positional embedding (RoPE), which has been adopted in nearly all LLMs.

Before we do one-hot embedding, we need to tokenize natural language.

- Definition: Converting text into tokens (small units) before feeding it into a model.
- **Purpose:** Makes the text interpretable for the model, facilitating further processing like embedding and sequence modeling.

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• Many other tokenizations. Libraries like NLTK, spaCy provide basic tokenization. transformers library by Hugging Face for transformer-specific tokenization.

#### **Cost Analysis**

$$\begin{split} \mathtt{MHA}(X) &= X + \sum_{h=1}^{H} W^h_O W^h_V X \mathtt{SA}^h(X), \\ \mathbb{F}(\mathbf{x}) &= W_1^\top \mathrm{ReLU}(W_2 \mathbf{x} + \mathbf{b}). \end{split}$$

In practice, it is often choose

$$d_{\text{key}} = d_{\text{model}}/H, \quad d_{\text{FF}} = 4d_{\text{model}}.$$

• Storage: 
$$4d_{\text{model}}^2 + 8d_{\text{model}}^2$$

• Computation:

• MHA: 
$$4nd_{\text{model}}^2 + \frac{d_{\text{model}}n^2}{d_{\text{model}}n}$$
  
• FF:  $8d_{\text{model}}^2n$ .

• Tokenwise operations can be parallelized. The total cost depends on the sequence length **qudratically**. This is especially bad for inference!!

#### **Training Deep Transformers Need Many Tricks**

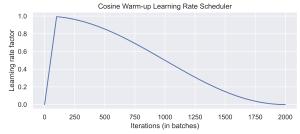
• Scaled dot-product attention

$$\mathbb{A}_{W_K,W_Q}(X) = \sigma\left(\frac{1}{\sqrt{d_k}}(W_K X)^\top (W_Q X)\right) \in \mathbb{R}^{n \times n},$$

• Layer normalization + residual connection:

$$\begin{split} \tilde{X}^{(\ell-1)} &= \mathbf{LN}(X^{(\ell-1)}) \\ X^{\ell} &= \mathbb{F}\left(\tilde{X}^{(\ell-1)} + \mathtt{MHA}(\tilde{X}^{(\ell-1)})\right) \end{split}$$

- AdamW optimizer with  $(\beta_1 = 0.9, \beta_2 = 0.98)$  and gradient clipping.
- Learning rate warmup + Cosine decay.



- The original paper https://arxiv.org/abs/1706.03762
- Annotated Transformer https://jalammar.github.io/illustrated-transformer/
- Illustrated Transformer https://poloclub.github.io/transformer-explainer/

#### BERT

- Developed by Google.
- Bidirectional: Unlike traditional models that read text unidirectionally, BERT reads the entire sequence of words at once.
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#### **Pre-training Tasks:**

- Masked Language Model (MLM): Randomly masks words in the sentence and predicts them.
- Next Sentence Prediction (NSP): Predicts if a given sentence logically follows another.

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**Fine-tuning:** Adapts pre-trained BERT for various downstream tasks like question answering, sentiment analysis, etc.

### **GPT** (Generative Pre-trained Transformer)

• Next-token prediction (autoregressive model):

$$\max_{\theta} \sum_{i=1}^{n} \log P_{\theta}(x_i | x_1, \dots, x_{i-1}).$$

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Text Generation:

 $text = [\langle bos \rangle]$  or [some context] while True: logit = decoder(embed(text))index = top(logit[-1])token = vocabulary(index)if token  $== \langle eos \rangle$ : break text.append(token) return text

#### Practice

- Pre-train models in large dataset. Fine-tune models on down-stream tasks.
- Fine-tuning needs to retrain our model, which is not user-friendly.
- Next-token prediction enables capability of doing in-context learning.

```
In the following lines, the symbol -> represents a simple mathematical operation.
100 + 200 -> 301
838 + 520 -> 1359
343 + 128 -> 472
647 + 471 -> 1119
64 + 138 -> 203
498 + 592 ->
```

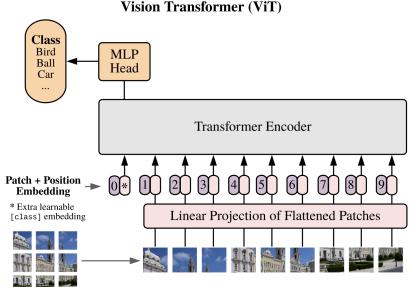
#### Answer:

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Prompt!

GPT and its focus on next-token prediction have fundamentally transformed how pre-trained models are utilized, marking a significant step toward AGI. The transition from BERT to GPT represents a **major breakthrough** in this evolution.

## Vision Transformer (ViT)



#### Vision Transformer (ViT)

- Transformers or attention-based models are versitle in many applications.
- Next-token prediction is powerful and **it implicitly performs multi-task learning**. The latter might be the major reason of why GPT is so successful.